Spatially Coherent 3D Distributions of HI and CO in the Milky Way

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The Diffuse (Galactic) Gamma-Ray Sky



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The Idea: Reconstructing the 3D Gas Distributions

- ✤ Gas on (circular) paths around the Galactic Centre
- Narrow emission lines become Doppler-shifted



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Problems:

- I. Velocity \rightarrow distance is ambiguous!
- II. True orbits are unknown! ~5-10% deviations!









Bayes' law:
$$P(\rho_{\text{HI}}, \rho_{\text{CO}}, \mathbf{v}, ... | d) = \frac{P(d | \rho_{\text{HI}}, \rho_{\text{CO}}, \mathbf{v}, ...) \cdot P(\rho_{\text{HI}}, \rho_{\text{CO}}, \mathbf{v}, ...)}{P(d)}$$

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We reconstruct a set of samples $\{\rho_{\text{HI},i}, \rho_{\text{CO},i}, v_i\}_{i=1...N}$ that approximate the posterior distribution

For more detail: arXiv:1901.11033

A Model for the Gas Distributions



✤ Key requirement: Spatial coherence

- ↔ Homogeneous (log)normal Gaussian random fields $g(\vec{x})$:
 - ✤ Generated e.g. by correlating random numbers

Superimposed:

- 1) Radial profile: Milky Way is (roughly) axisymmetric
- 2) Z-profile: Milky Way is disk-shaped

A Model for the Gas Distributions





A Model for the Gas Distributions





A Model for the Line-Of-Sight Velocity



A Model for the Line-Of-Sight Velocity



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(Ou et al (2023))

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R [kpc]

A Model for the Line-Of-Sight Velocity



The Emission Line Spectra: HI and CO



Calculate synthetic data as line-of-sight integral: $dI_v = -I_v \kappa_v ds + j_v ds$

The Emission Line Spectra: HI and CO



The Emission Line Spectra: HI and CO



Results: Top-down view (global)



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Results: Top-down view (global)



Results: Top-down view (global)







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Results: Top-down view (local)



Results: A comparison to dust (local)



Results: Sky-view Proton Column Density







Results: Sky-view Proton Column Density



Results: Sky-view Proton Column Density







Conclusions

Coherent picture of Milky Way gas distribution

Uncertainty estimation possible with multiple samples

High resolution near-by

Publication in preparation \rightarrow results available soon!









Backup 1.1: Metric Gaussian Variational Inference



Bayes' theorem:





- 1. Guess a starting point for the mean
- 2. Draw samples from the approximated posterior distribution at the mean
- **3. Estimate "distance"** to true posterior via Kullback-Leibler-Divergence
- 4. Update mean estimation
- 5. Repeat

Backup 1.2: MGVI-Sampling: Inverse Fisher Metric as Covariance

How to sample from the (approximated) Posterior? → Approximate Covariance by inverse **Fisher metric**





With Fisher metric of likelihood $I_d(\xi) = \left\langle \frac{\partial \mathcal{H}(d|\xi)}{\partial \xi} \frac{\partial \mathcal{H}(d|\xi)}{\partial \xi^{\dagger}} \right\rangle_{\mathcal{P}(d|\xi)}$

Application of (inverse of) this **scales linearly with model parameters** due to implicit operators. There is no need to store the full covariance matrix at any point!

Backup 1.3: MGVI: Optimising the Mean

How to optimise the estimate of the mean?

Evaluate Kullback-Leibler-Divergence stochastically:

$$\mathcal{D}_{\mathrm{KL}}\left(\mathcal{G}(\xi|\bar{\xi},\Xi(\hat{\xi}))||\mathcal{P}(\xi|d)\right) \widehat{=} \langle \mathcal{H}(d,\xi) \rangle_{\mathcal{G}(\xi|\bar{\xi},\Xi(\hat{\xi}))}$$
$$\approx \frac{1}{N} \sum_{i=1}^{N} \mathcal{H}(d,\bar{\xi}+\Delta\xi_*^i)$$

 $\begin{array}{c} \mathcal{G}(\xi|\bar{\xi},\Xi)\\ \hline \\ \text{Infer these} \\ \hline \\ \text{Approximate those} \\ \end{array}$

gradients via autodifferentiation

And minimise w.r.t the mean parameters



Backup 2: Verification of the Method

20 10 y [kpc] -10-20 10 20 -20 -10 0 x [kpc]

Ground truth





